

Probability Calculus

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VARIANCE

MOMENTS

EMPIRICAL DISTRIBUTIONS

Plan for Today

1. Calculating EX – examples cont.
2. Variance
3. Moments
4. Empirical distributions
5. Intro to random vectors



Expected value – cont

Calculating $\mathbb{E}X$ based on the CDF –

reminder *Let X be a non-negative random variable.*

(i) *If $\int_0^\infty \mathbb{P}(X > t)dt < \infty$, then X has an expected value and $\mathbb{E}X = \int_0^\infty \mathbb{P}(X > t)dt$.*

(ii) *If $p \in (0, \infty)$ and $\int_0^\infty pt^{p-1}\mathbb{P}(X > t)dt < \infty$, then X^p has an expected value and $\mathbb{E}X^p = \int_0^\infty pt^{p-1}\mathbb{P}(X > t)dt$.*

Examples

- geometric distribution
- exponential distribution
- p -th moments
- non-discrete non-continuous RV



Variance

1. Definition

Let X be a random variable such that $\mathbb{E}|X| < \infty$ and $\mathbb{E}(X - \mathbb{E}X)^2 < \infty$. The **variance** of X is defined as $D^2X = \text{Var}X = \mathbb{E}(X - \mathbb{E}X)^2$.

The **standard deviation** of variable X is the square root of the variance: $\sigma_X = \sqrt{D^2X}$.

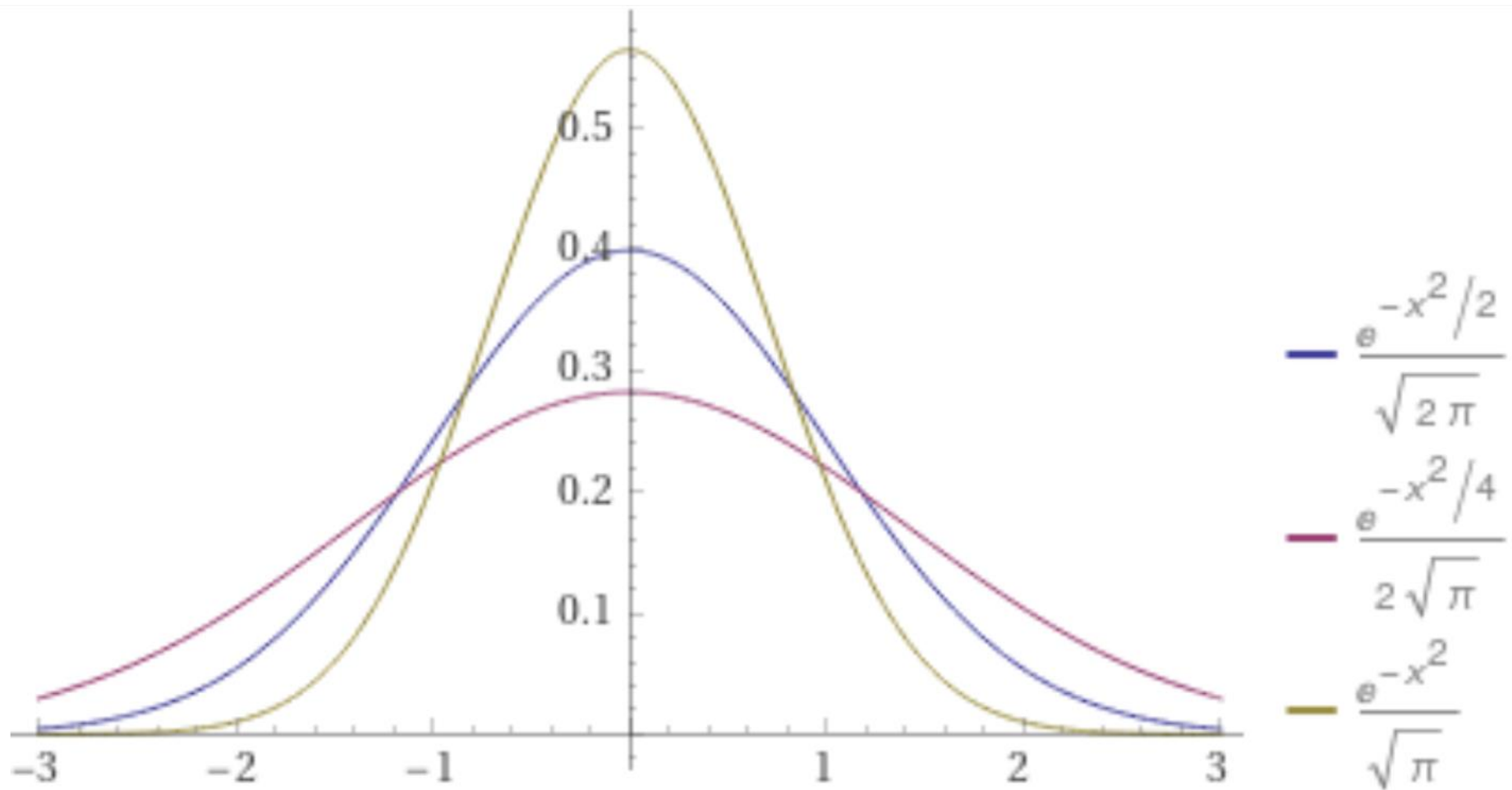
2. Properties

- depends on distribution only
- exists if single condition on $\mathbb{E}X^2$, if limited
- simplified calculations: $D^2X = \mathbb{E}X^2 - (\mathbb{E}X)^2$

- interpretation



Variance – interpretation



Variance – cont.

3. Examples:

- interpretation
- die roll
- uniform distribution

4. Properties, theorem:

Let X be a random variable with a variance.

(i) $D^2 X \geq 0$, and the equality holds if and only if there exists a value $a \in \mathbb{R}$ such that $\mathbb{P}(X = a) = 1$.

(ii) $D^2(bX) = b^2 D^2 X$ for any $b \in \mathbb{R}$.

(iii) $D^2(X + c) = D^2 X$ for any $c \in \mathbb{R}$.



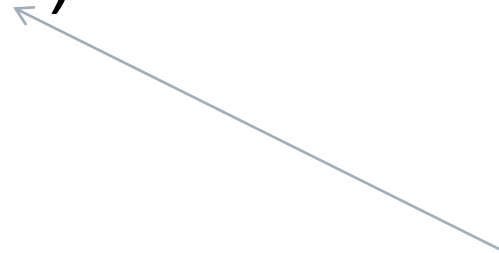
Variance – cont. (2)

5. Parameters of the normal distribution:

$$N(m, \sigma^2)$$



mean



variance



Moments

1. Definitions

For $p \in (0, \infty)$, we define:

(i) the **absolute moment** of rank p for random variable X as $\mathbb{E}|X|^p$ (if this value is finite);

For $p \in \mathbb{N}$, we define:

(ii) the **moment** of rank p for random variable X as $\mathbb{E}X^p$ (provided that the p -th absolute moment exists);

(iii) the **central moment** of rank p for random variable X as $\mathbb{E}(X - \mathbb{E}X)^p$ (provided that the p -th absolute moment exists).



Moments: skewness, kurtosis

2. Definitions

Let X be a random variable such that $\mathbb{E}|X|^3 < \infty$.

*The **skewness** of X is*

$$\alpha_3 = \frac{\mathbb{E}(X - \mathbb{E}X)^3}{(D^2X)^{3/2}} = \frac{\mathbb{E}(X - \mathbb{E}X)^3}{\sigma_X^3}.$$

Let X be a random variable such that $\mathbb{E}|X|^4 < \infty$.

*The **kurtosis** of X is*

$$\alpha_4 = \frac{\mathbb{E}(X - \mathbb{E}X)^4}{(D^2X)^2} - 3 = \frac{\mathbb{E}(X - \mathbb{E}X)^4}{\sigma_X^4} - 3.$$

3. Example: standard normal distribution



Empirical distributions

1. In reality, we frequently do not know the distributions of random variables, and work with *samples* instead.

2.

*Let X_1, X_2, \dots, X_n be random variables with unknown distributions. An **Empirical distribution (measure)** for this sample is*

$$\mu_n(A) = \frac{1}{n} \sum_{i=1}^n \delta_{X_i}(A) = \frac{|\{i \leq n: X_i \in A\}|}{n},$$



Empirical distributions – cont.

3. An empirical distribution function of the sample X_1, X_2, \dots, X_n is the function $F: \mathbb{R} \rightarrow [0, 1]$, such that
- $$F_n(t) = \mu_n((-\infty, t]) = \frac{|\{i \leq n: X_i \leq t\}|}{n}.$$

this is the CDF of the empirical distribution

4. A Quantile of rank p of the sample X_1, \dots, X_n is any number x_p , such that
- $$\mu_n((-\infty, x_p]) \geq p$$
- $$\mu_n([x_p, \infty)) \geq 1 - p.$$



Empirical distributions – cont (2)

5. A Sample mean for X_1, X_2, \dots, X_n is equal to $m = \frac{X_1 + X_2 + \dots + X_n}{n}$,
i.e. the arithmetic mean of X_1, X_2, \dots, X_n .

6. A sample variance for X_1, X_2, \dots, X_n is equal to $s^2 = \frac{1}{n} \sum_{i=1}^n (X_i - m)^2$,
where m is the sample mean.



the mean and the variance of the empirical distribution



Random vectors

1. A random vector (X_1, X_2, \dots, X_n)
2. The joint distribution of a random vector:

The (joint) distribution of a random vector $X = (X_1, X_2, \dots, X_n)$ is a probability measure μ_X defined over $(\mathbb{R}^n, \mathcal{B}(\mathbb{R}^n))$, such that $\mu_X(A) = \mathbb{P}(X \in A)$.

3. Marginal distributions:

$$\mu_{X_i}(B) = \mathbb{P}(X_i \in B) \text{ for } B \subseteq \mathbb{R},$$

such that for $A = \underbrace{\mathbb{R} \times \dots \times \mathbb{R}}_{i-1} \times B \times \underbrace{\mathbb{R} \times \dots \times \mathbb{R}}_{n-i}$

we have

$$\mathbb{P}(X_i \in B) = \mathbb{P}((X_1, X_2, \dots, X_n) \in A) = \mu_X(A).$$



Random vectors – cont.

4. Example: joint distribution is more than the aggregate of marginal distributions.
5. Cumulative distribution function:

The cumulative distribution function of a random vector (X, Y) is a function $F_{(X,Y)} : \mathbb{R}^2 \rightarrow [0, 1]$, such that $F_{(X,Y)}(s, t) = \mathbb{P}(X \leq s, Y \leq t)$.

6. No simple definitions of quantiles...



Random vectors – types.

7. A discrete RV

A random vector (X, Y) is **discrete**, if there exists a countable set $S \subseteq \mathbb{R}^2$, such that $\mu_{(X,Y)}(S) = 1$.

8. Components are also discrete, marginals obtained by summation

9. A continuous RV

A random vector (X, Y) is **continuous**, if there exists a density function, i.e. a function $g : \mathbb{R}^2 \rightarrow [0, \infty)$, such that for any $A \in \mathcal{B}(\mathbb{R}^2)$, we have $\mu_{(X,Y)}(A) = \iint_A g(x, y) dx dy$.



